MRU H





This fifth generation MRU is specially designed for heave compensation applications.

Typical applications

The MRU H is specially designed for motion measurements in marine applications requiring highly accurate heave measurements in environments with extreme horizontal accelerations. This MRU is an ideal sensor for roll, pitch and heave compensation of offshore cranes and echo sounders. The MRU H can also be used for typical ship motion monitoring applications such as helideck motion monitoring, hydroacoustic positioning systems, as well as hull stress monitoring.

Function

The MRU H incorporates three highly accurate accelerometers and three Micro-Electro-Mechanical-Structures (MEMS) angular rate gyros. This unit achieves high reliability by using solid state sensors with no rotational or mechanical wear-out parts.

The unit is delivered with Windows based configuration and data presentation software. In this software vector arms from where the MRU is mounted to center of gravity (CG) and two individually configurable monitoring points (MPs), can be defined. The heave measurements can be output in four different locations (the MRU itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet port. Typical monitoring point is the transducer head or the crane tip.

Output variables

The MRU H outputs roll, pitch and heave together with linear acceleration in 3-axes. The MRU H outputs heave position, velocity and accelerations in adjustable frames. In addition roll and pitch angles and corresponding angular rate vectors are output.

PFreeHeave® Algorithm

The PFreeHeave algorithm uses past measurements to output a correct and phase-free heave from the MRU. PFreeHeave has an advantage in long swell conditions and for applications that can utilize a heave signal that is delayed some minutes, typical seabed mapping applications.

External inputs

The MRU H accepts input of external speed and heading information on separate serial lines or Ethernet for improved accuracy in heave, roll and pitch during turns and accelerations. For time synchronization the MRU accepts 1-second time pulse (1PPS) input on a TTL line (XIN) or as RS-232/422 signal.

Digital I/O protocols

For this fifth generation MRU data is available through both Ethernet interface and serial lines enabling easy distribution of MRU data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- High accuracy heave measurements even in dynamic environments
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Meets IHO special order requirements
- Small size, light weight and low power consumption
- No limitation to mounting orientation
- Each MRU delivered with Calibration Certificate
- Selectable communication protocols in the Windows based MRU configuration software
- 2-year warranty



TECHNICAL SPECIFICATIONS

MRU H

ORIENTATION OUTPUT

Angular orientation range #180° Resolution in all axes 0.001° Accuracy 1, 2) roll, pitch

(for a ±5° amplitude) 0.05° RMS

GYRO OUTPUT

Angular rate range ±100°/s
Angular rate noise 0.1°/s RMS
Scale factor error 0.2 % RMS

ACCELERATION OUTPUT

Acceleration range (all axes) ±30 m/s2
Acceleration noise 0.002 m/s2 RMS
Acceleration accuracy 0.01 m/s2 RMS
Scale factor error 0.02% RMS

HEAVE OUTPUT

Output range Heave accuracy for 0 to 25 s motion periods (real-time)

Heave accuracy for 10 s

motion period (real-time)

Heave accuracy for 0 to 50 s

motion periods (delayed)

Heave velocity accuracy

ELECTRICAL

Voltage input Power consumption

Serial ports:

Com2

00...2

Com3 & Com4

Analog channels

(junction box) Ethernet output ports

Ethernet UPD/IP Data output rate (max)

Timing

 ± 50 m, adjustable

5 cm or 5% whichever is highest

RMS)

1 cm or 3% whichever is highest

(RMS)

2 cm or 2% whichever is highest (RMS)

0,01 m/s RMS

0,01 111/0 11110

10 to 36 V DC Max 8 W (typical 7.2 Watts)

nax o w (cypical 7.2 wacco

Bidirectional RS-422 Bidirectional RS-422 from junction

box, user configurable RS-232, RS-

422

Input only, user configurable RS-232, RS-422

202, 110 422

4, ±10 V, 14 bit resolution 5

10/100 Mbps 200 Hz < 1 ms INPUT FORMATS

NMEA 0183, incl. HDT, HDM, ZDA, GGA, VTG, VHW, VBW or MRU Normal format $\,$

DATA OUTPUT PROTOCOLS

- MRU normal - Sounder - NMEA 0183 proprietary - EM3000 - Atlas Fansweep - TSS1 - Seapath binary 23, 25, 26 - PFreeHeave®

OTHER DATA

MTBF (computed) 50000 h MTBF (service history based) 100000 h

Material Anodised aluminium
Connector (MIL. spec.) Souriau 851-36RG 16-

26850

- KM binary

WEIGHT AND DIMENSIONS

Weight 2.2 kg

Dimensions Ø 105 x 140 mm (4.134" x

5.525")

ENVIRONMENTAL SPECIFICATIONS

Operational temperature range $-5\,\,^{\circ}\text{C}$ to +55 $^{\circ}\text{C}$ Storage temperature range $-25\,\,^{\circ}\text{C}$ to +70 $^{\circ}\text{C}$ Enclosure protection IP66 Vibration IEC 60945/EN 60945

ELECTROMAGNETIC COMPATIBILITY

Compliance to EMCD,

immunity/emission IEC 60945/EN 60945

- When the MRU is exposed to a combined two-axes sinusoidal angular motion with 10 minutes duration.
- $^{2)}$ When the MRU is stationary over a 30-minute period.

Specifications subject to change without any further notice.



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